

Oil Immersed Transformer Hot-Spot Temperature (HST) Models

We introduce two models based on the IEEE [1] and IEC [2] loading guides to compute the HST of a transformer winding. The models are solved numerically using arbitrary load and top oil temperature profiles. The results are then compared to highlight relative characteristics of the models.

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The Transformer Loss of Life (LoL) is based on knowing the HST [3]. It is generally adopted that the HST is given by (1).

$$\theta_H = \theta_A + \Delta\theta_{TO} + \Delta\theta_H = \theta_{TO} + \Delta\theta_H \dots (1a)$$

$$\theta_{TO} = \theta_A + \Delta\theta_{TO} \dots (1b)$$

Where:

θ_H is the HST;

θ_A is the average ambient temperature during the load cycle;

$\Delta\theta_{TO}$ is the top oil temperature rise; and

$\Delta\theta_H$ is hot-spot to top oil temperature rise.

Traditional models [1, 2] estimate the HST based on (1) and require inputs that include: (i) parameters specific to the transformer; and (ii) real-time measurements of ambient temperature, top oil temperature and load current. In recent years transformer manufacturers have included fibre optic sensors (FOS) distributed throughout the windings which conveniently provide an accurate HST measurement leading to a better estimate of the LoL. There are still many transformers in the field that do not incorporate FOS and rely on traditional models for maximising their useful lifespan. This work describes two traditional models for estimating the HST in oil immersed transformers; the models are solved for the HST and compared.

HST MODELS

In our applications, the top oil temperature is provided (measured) and therefore analysis is limited to models that consider only the hot-spot to top oil temperature rise.

Model 1: The model referred to in Clause 7 [1] as 'transient heating equation' is based on work by Kennelly [4] who showed that the winding temperature rise above room temperature is exponential, and Cooney [5] who proposed that the winding temperature rise above top oil temperature and the top oil temperature rise can be treated separately. The model assumes an average ambient temperature of 30°C and step changes in load.

The transient winding HST rise over top oil temperature is given by (2).

$$\Delta\theta_H = (\Delta\theta_{H,u} - \Delta\theta_{H,i}) \left(1 - e^{-\frac{t}{\tau_w}}\right) + \Delta\theta_{H,i} \dots (2)$$

Where:

t is the duration of the load;

$\Delta\theta_H$ is hot-spot to top oil temperature rise.

$\Delta\theta_{H,u}$ is the ultimate winding hottest-spot rise over top oil temperature for the load;

$\Delta\theta_{H,i}$ is the initial winding hottest-spot rise over top oil temperature for $t=0$; and

τ_w is the winding time constant at the hot-spot location (4.8 minutes [6]).

The initial and ultimate HST rises over top oil temperature are given by (3).

$$\Delta\theta_{H,i} = \Delta\theta_{H,R} K_i^{2m} \dots (3a)$$

$$\Delta\theta_{H,u} = \Delta\theta_{H,R} K_u^{2m} \dots (3b)$$

Where:

m is an empirically derived exponent to calculate the variation of $\Delta\theta_H$ with changes in load (this varies with the type of cooling and is equal to 0.8 for ONAN cooling [1]);

K_u is the ratio of ultimate load to rated load;

K_i is the ratio of initial load to rated load; and

$\Delta\theta_{H,R}$ is the winding hottest-spot rise over top-oil temperature at rated load (typical values range from 20°C to 35°C [6]).

Model 2: The most recent model [2], is based on work by Swift [7] who proposed a thermal model of a power transformer based on heat transfer theory with an equivalent electrical circuit for determining the HST, shown in Figure 1.

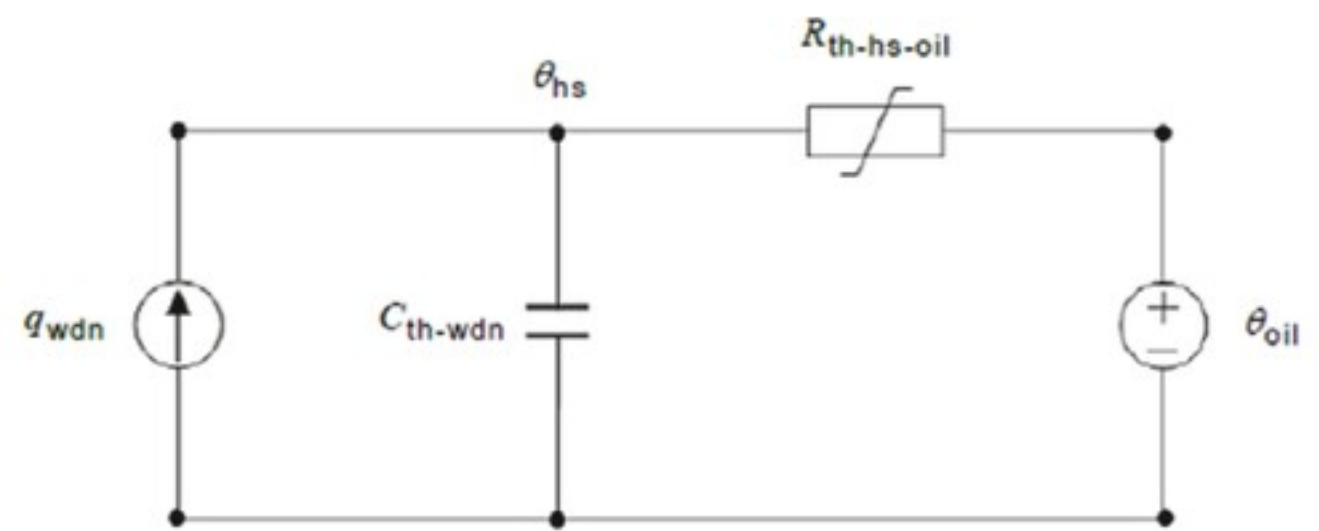


Figure 1 Thermal model of winding-to-oil heat transfer

The current source q_{wdn} is the heat generated by the winding losses, C_{th-wdn} is the thermal capacitance of the winding, $R_{th-hs-oil}$ is the non-linear winding to oil thermal resistance, and θ_{hs} is the HST. Swift's model is further extended by considering the hot-spot rise dynamic as differences between the fundamental hot-spot rise and the effect of the varying oil flow that influences the HST given by (4).

$$\Delta\theta_h(t) = \Delta\theta_{h1}(t) - \Delta\theta_{h2}(t) \dots (4)$$

$\Delta\theta_{h1}$ represents the change in the fundamental hot-spot rise given by (5).

$$\Delta\theta_{h1}(t) = (k_{21}H g_r K^y - \Delta\theta_{h1,i}) \left(1 - e^{-\frac{t}{k_{22}\tau_w}}\right) + \Delta\theta_{h1,i} \dots (5)$$

$\Delta\theta_{h2}$ represents the varying rate of oil flow past the hot-spot, a phenomenon which changes much more slowly and given by (6).

$$\Delta\theta_{h2}(t) = ((k_{21} - 1)H g_r K^y - \Delta\theta_{h2,i}) \left(1 - e^{-\frac{k_{22}t}{\tau_0}}\right) + \Delta\theta_{h2,i} \dots (6)$$

The combined effect of (5) and (6) account for the scenario where a sudden rise in the load current may cause an otherwise unexpectedly high peak in the HST rise, very soon after the sudden load change [2]. Additionally, k_{21} and k_{22} are dimensionless parameters and shape (5) and (6) according to Table 1.

Characteristic	Small transformers	Medium and large power transformers						
	ONAN	ONAN restricted ^a	ONAN	ONAF restricted ^a	ONAF	OF restricted ^a	OF	OD
Oil exponent x	0,8	0,8	0,8	0,8	0,8	1,0	1,0	1,0
Winding exponent y	1,6	1,3	1,3	1,3	1,3	1,3	1,3	2,0
Constant k_{11}	1,0	0,5	0,5	0,5	0,5	1,0	1,0	1,0
Constant k_{21}	1,0	3,0	2,0	3,0	2,0	1,45	1,3	1,0
Constant k_{22}	2,0	2,0	2,0	2,0	2,0	1,0	1,0	1,0
Time constant τ_w , min	180	210	210	150	150	90	90	90
Time constant τ_0 , min	4	10	10	7	7	7	7	7

^a If a winding of an ON- or OF-cooled transformer is zigzag-cooled, a radial spacer thickness of less than 3 mm might cause a restricted oil circulation, i.e. a higher maximum value of the function $\Delta\theta_h(t)/\Delta\theta_{ht}$ than obtained by spacers ≥ 3 mm.

Table 1 Recommended thermal characteristics for exponential equations [2]

multiplied by the time index shown in the graphs. Distributions of Load Factor (LF) and top oil temperature, shown in Figures 2 and 4, are created for the purpose of highlighting the characteristics of the models.

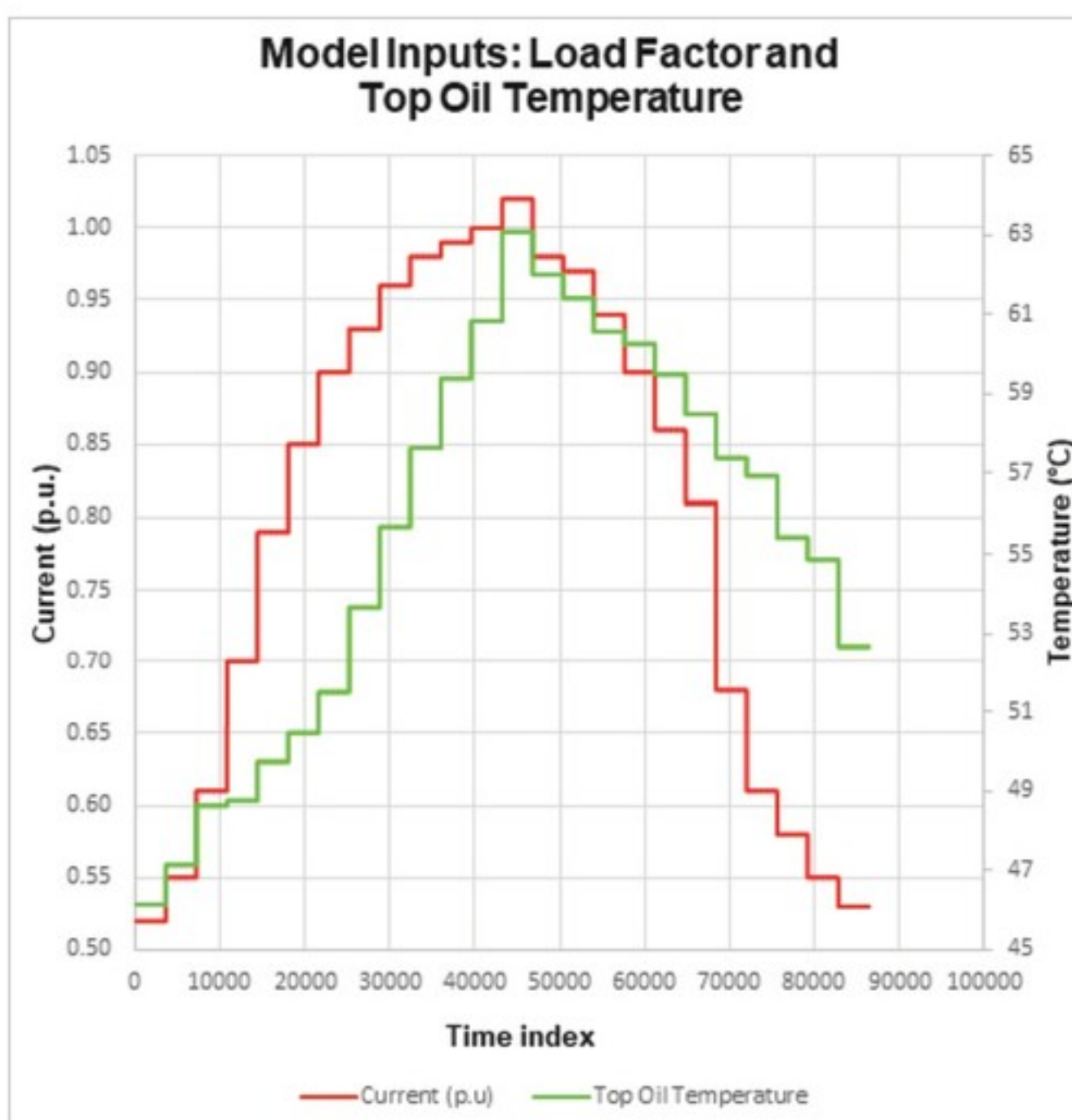


Figure 2 Load Factor and top oil temperature profiles

MODEL SOLUTIONS

In this section equations are solved numerically for various scenarios. The actual time is equal to the time increment, set to 0.0167 minutes,

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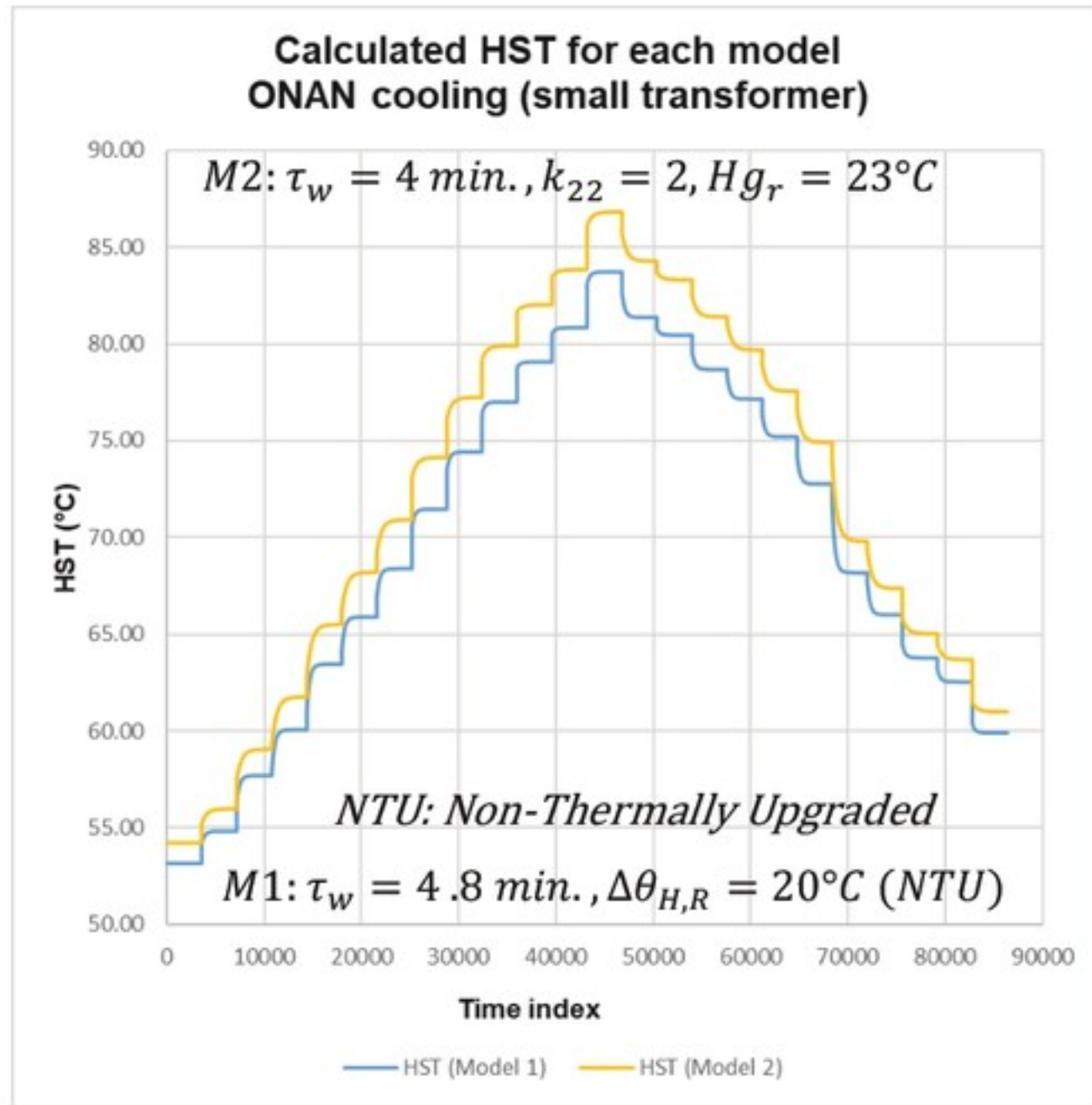


Figure 3 HST model comparison

In the case where k_{21} is set to 1, (6) vanishes because the initial value $\Delta\theta_{h2,i}$ is zero leaving only (5). Equations (5) and (2) with (3b) reduce to the same functional form; noting the difference in time constants, τ_w in (2) and $k_{22} \tau_w$ in (5). Solutions to (1) are shown in Figure 3. As expected, the HST distributions essentially follow the step responses in the top oil temperature profile and also exhibit the exponential growth and decay in accordance with the LF. The maximum variation, Model 2 minus Model 1, is $\sim 3.2^\circ\text{C}$ and occurs at the start of the peak of the LF profile. This is due to the differences in parameters, otherwise both models yield no variation.

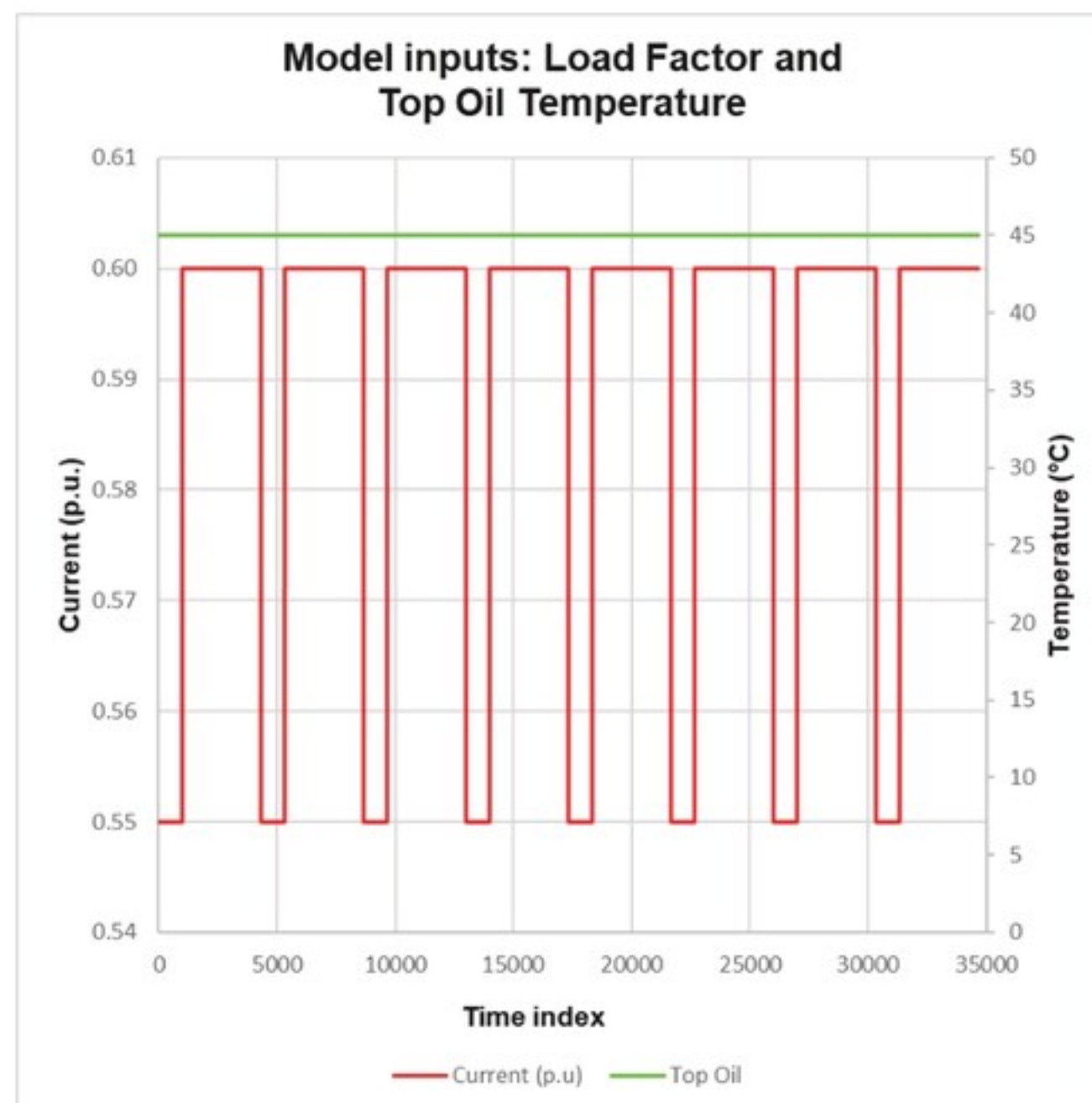


Figure 4 Load Factor and top oil temperature profiles

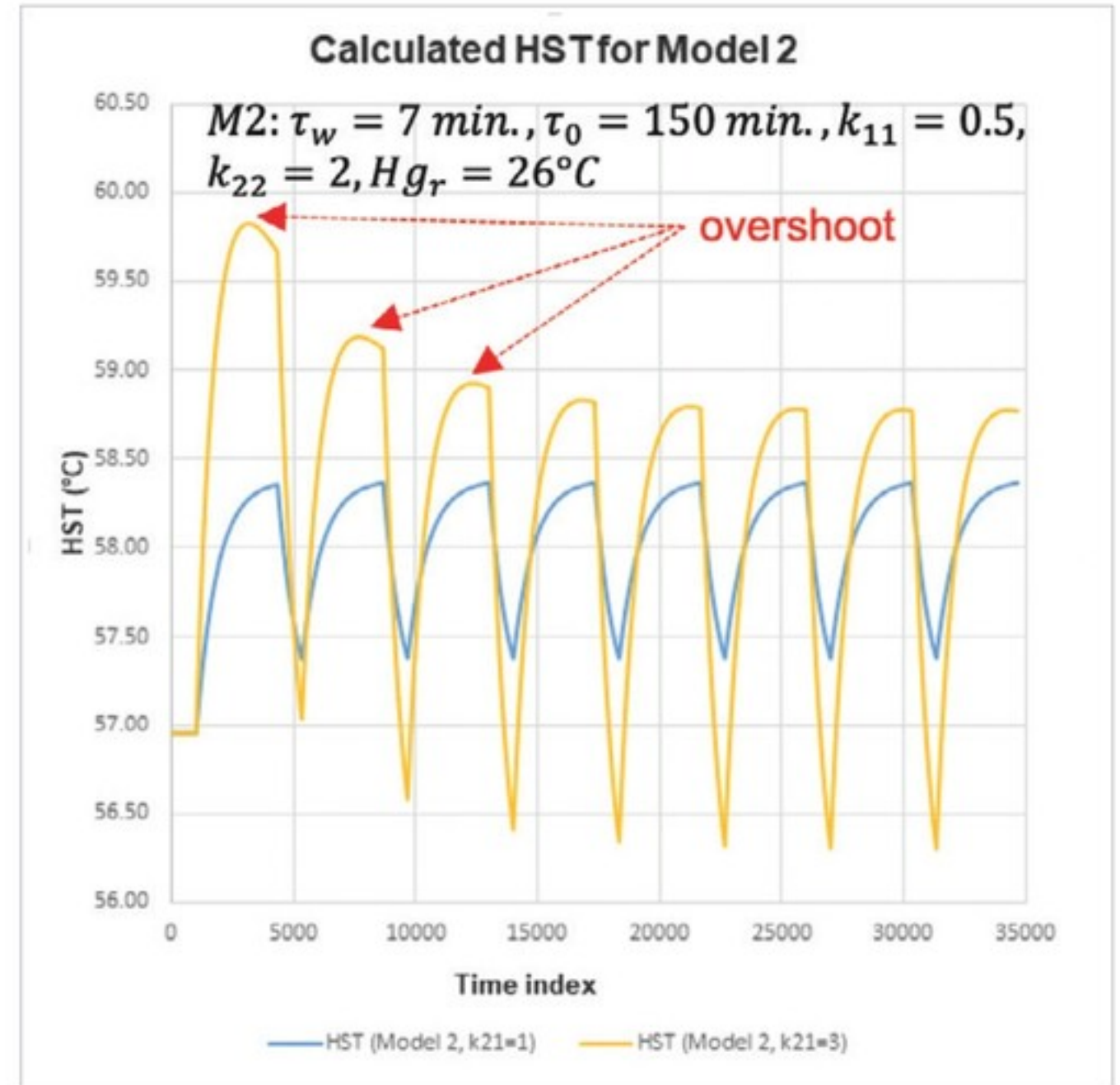


Figure 5 HST Model 2

The thermal effect of the oil on the winding HST rise in Model 2 is further investigated by setting k_{21} to 1 and 3 and by applying the distributions shown in Figure 4. When k_{21} is set to 1, the effect of oil is not included and the transient behaviour is solely due to the winding constant. Setting k_{21} to 3 ensures the contribution of the oil time constant in (6) and with (4) now resulting in a subtraction of two first order step responses. The effect is shown in Figure 5, with the response initially exhibiting significant overshoot in the first three excursions and eventually settles to a final value. The effect is due to the inertia of the oil, and is more prevalent in ONAN^a and ONAF^a transformers where oil circulation is restricted, refer to Table 1. The slow decay in the response is due to the oil constant which is ~ 21 times that of the winding constant.

TRANSFORMER MONITORING

CHK Power Quality Pty Ltd offers the Miro-F TxM Transformer Monitor and Logger (TxM), an instrument purposely suited for comprehensive monitoring of transformer health and can provide LoL calculations based on the IEC and IEEE Standards.

The TxM includes two temperature sensors which can be software configured to measure the top oil and ambient temperatures. Where the transformer is equipped with multiple winding temperature sensors the TxM, together with the Miro Auxiliary I/O module (MiroAux), can utilise these inputs in its LoL calculations.

Setting up and configuring the TxM requires the user to populate a template with relevant transformer ratings and other known parameters specific to the transformer. Alternatively, the user can use default values, provided in the TxM, for parameters that are not readily available on the transformer's name plate.

The TxM together with the MiroAux can expand the monitoring to include geomagnetic DC current; dissolved gases such as oxygen; moisture; on load tap changer (OLTC) operation; bushing leakage current; and fan operation. All these parameters can, not only be displayed alongside critical power quality information, but also correlated for in depth analysis. **T&D**

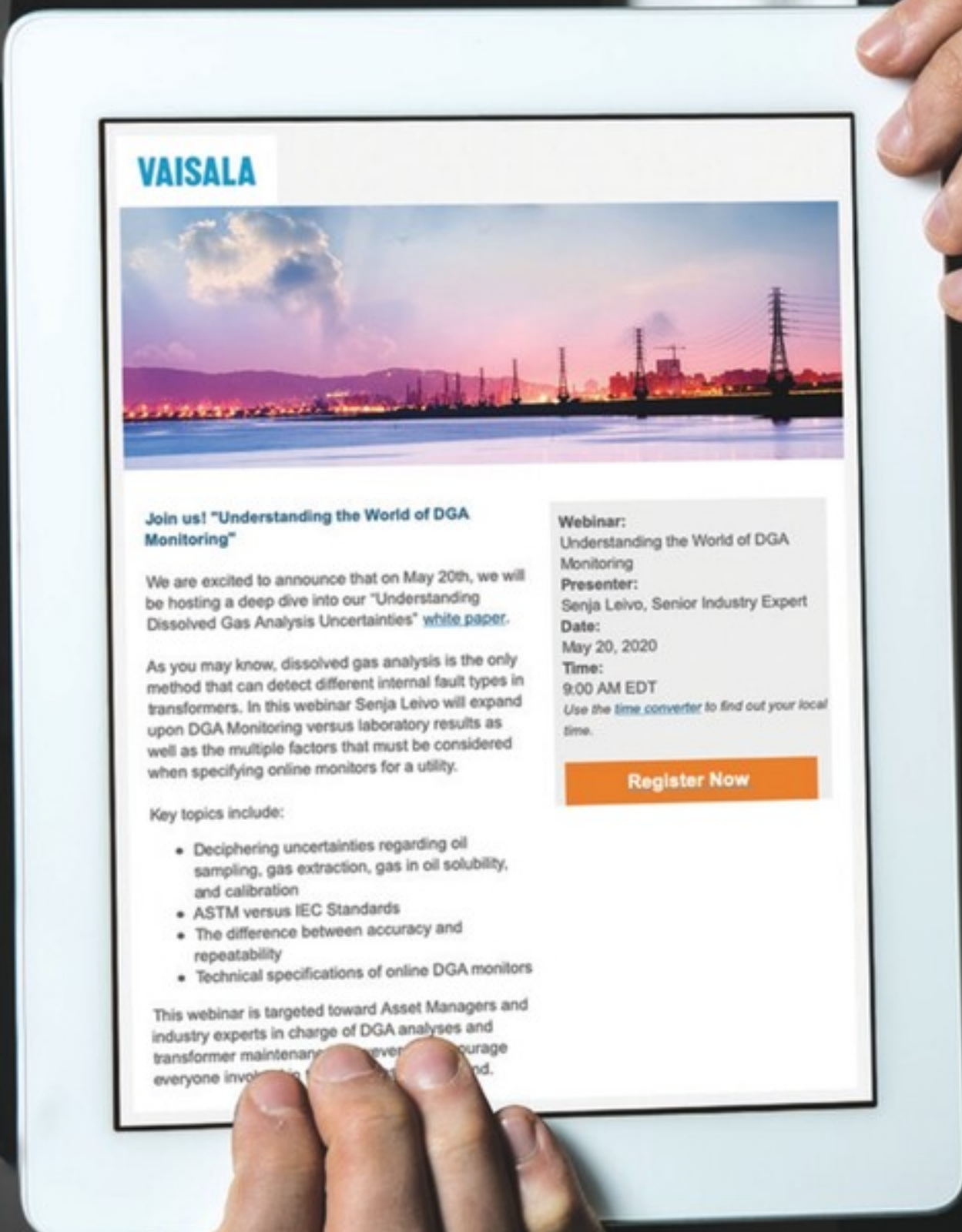


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